

- With torque sensor
- Compact structure
- EtherCAT[®] communication
- Optimized assembly
- High torque density
- Lightweight
- Universal robotic joint module



「Bionic 7-DoF
robot arm」



HN-115

O.D (mm)	110
Length (mm)	103
Hollow hole (mm)	7
Working voltage (Vdc)	48
Power (W)	434
Rated current (A)	9.1
Peak current (A)	22.6
Rated torque (Nm)	81.5
Peak torque (Nm)	203
Rated speed (rpm)	42
Max. speed (rpm)	60
Weight (kg)	2.4
Repeatability (arcsec)	20

HN-90

O.D (mm)	90
Length (mm)	89
Hollow hole (mm)	7
Working voltage (Vdc)	48
Power (W)	408
Rated current (A)	8.5
Peak current (A)	21.2
Rated torque (Nm)	54.1
Peak torque (Nm)	134.9
Rated speed (rpm)	40
Max. speed (rpm)	86
Weight (kg)	1.5
Repeatability (arcsec)	20

HN-70

O.D (mm)	70
Length (mm)	72
Hollow hole (mm)	4
Working voltage (Vdc)	48
Power (W)	120
Rated current (A)	2.5
Peak current (A)	8.9
Rated torque (Nm)	12.5
Peak torque (Nm)	45
Rated speed (rpm)	90
Max. speed (rpm)	120
Weight (kg)	0.5
Repeatability (arcsec)	20



Coming X Soon Linear actuator "LA series"

For more details please contact **cpc**

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